# HEF4015B

Dual 4-bit static shift register Rev. 10 — 26 November 2021

### 1. General description

The HEF4015B is a dual edge-triggered 4-bit static shift register (serial-to-parallel converter). Each shift register has a serial data input (nD), a clock input (nCP), four fully buffered parallel outputs (Q0 to Q3) and an overriding asynchronous master reset input (nMR). Information present on nD is shifted to the first register position, and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of nCP. A HIGH on nMR clears the register and forces Q0 to Q3 to LOW, independent of nCP and nD. Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of  $V_{DD}$ .

### 2. Features and benefits

- Wide supply voltage range from 3.0 V to 15.0 V
- CMOS low power dissipation
- High noise immunity
- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Complies with JEDEC standard JESD 13-B
- ESD protection:
  - HBM JESD22-A114F exceeds 2000 V
  - MM JESD22-A115-B exceeds 200 V
- Specified from -40 °C to +85 °C

### 3. Applications

- · Serial-to-parallel converter
- Buffer stores
- General purpose register

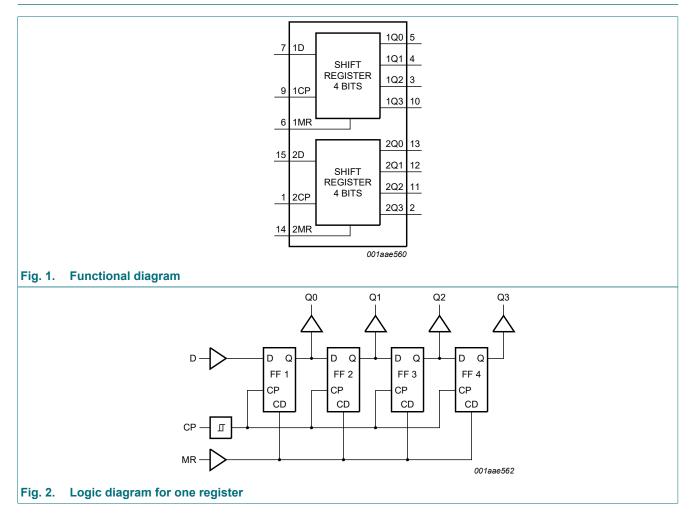
### 4. Ordering information

#### Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
HEF4015BT	-40 °C to +85 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

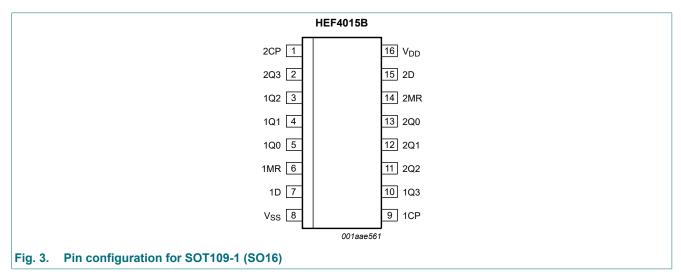
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### 5. Functional diagram



### 6. Pinning information

### 6.1. Pinning



### 6.2. Pin description

Table 2. Pin description		
Symbol	Pin	Description
1Q0, 1Q1, 1Q2, 1Q3	5, 4, 3, 10	parallel output
2Q0, 2Q1, 2Q2, 2Q3	13, 12, 11, 2	parallel output
1MR, 2MR	6, 14	master reset input (active HIGH)
1D, 2D	7, 15	serial data input
V <sub>SS</sub>	8	ground supply voltage
1CP, 2CP	9, 1	clock input (LOW-to-HIGH edge-triggered)
V <sub>DD</sub>	16	supply voltage

### 7. Functional description

#### Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Dn = either HIGH or LOW;  $\uparrow = positive-going transition; \downarrow = negative-going transition.$ 

number of clock	Input			Output				
pulse transitions	СР	D	MR	Q0	Q1	Q2	Q3	
1	1	D1	L	D1	Х	Х	Х	
2	1	D2	L	D2	D1	Х	Х	
3	1	D3	L	D3	D2	D1	Х	
4	1	D4	L	D4	D3	D2	D1	
	Ļ	Х	L	no change	no change	no change	no change	
	Х	Х	Н	L	L	L	L	

### 8. Limiting values

#### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{\rm I}$ < -0.5 V or $V_{\rm I}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
VI	input voltage		-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{\rm O}$ < -0.5 V or $V_{\rm O}$ > $V_{\rm DD}$ + 0.5 V	-	±10	mA
I <sub>I/O</sub>	input/output current		-	±10	mA
I <sub>DD</sub>	supply current		-	50	mA
T <sub>stg</sub>	storage temperature		-65	+150	°C
T <sub>amb</sub>	ambient temperature		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> = -40 °C to +85 °C	-	500	mW
Р	power dissipation	per output	-	100	mW

### 9. Recommended operating conditions

Table 5. Recommende	d operating conditions
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Symbol	Parameter	Conditions	Min	Тур	Мах	Unit
V <sub>DD</sub>	supply voltage		3	-	15	V
VI	input voltage		0	-	V <sub>DD</sub>	V
T <sub>amb</sub>	ambient temperature	in free air	-40	-	+85	°C
Δt/ΔV	input transition rise and fall rate	V <sub>DD</sub> = 5 V	-	-	3.75	µs/V
		V <sub>DD</sub> = 10 V	-	-	0.5	µs/V
		V <sub>DD</sub> = 15 V	-	-	0.08	μs/V

### 10. Static characteristics

#### Table 6. Static characteristics

 $V_{SS}$  = 0 V;  $V_{I}$  =  $V_{SS}$  or  $V_{DD}$  unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	T <sub>amb</sub> = -40 °C		T <sub>amb</sub> = 25 °C		T <sub>amb</sub> = 85 °C	
				Min	Мах	Min	Мах	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	l <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	l <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	/ <sub>OL</sub> LOW-level output voltage	l <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		V <sub>O</sub> = 0.5 V	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
lį –	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	20	-	20	-	150	μA
			10 V	-	40	-	40	-	300	μA
			15 V	-	80	-	80	-	600	μA
CI	input capacitance		-	-	-	-	7.5	-	-	pF

### **11. Dynamic characteristics**

#### Table 7. Dynamic characteristics

 $V_{SS} = 0 V$ ;  $C_L = 50 pF$ ;  $T_{amb} = 25 °C$ ; for test circuit see Fig. 7.

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula [1]	Min	Тур	Мах	Unit
t <sub>PHL</sub>	HIGH to LOW	nCP to Qn;	5 V	103 ns + (0.55 ns/pF)C <sub>L</sub>	-	130	260	ns
	propagation delay	see <u>Fig. 4</u>	10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
		nMR to Qn;	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
		see <u>Fig. 6</u>	10 V	34 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
				27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
t <sub>PLH</sub>	LOW to HIGH	nCP to Qn;	5 V	93 ns + (0.55 ns/pF)C <sub>L</sub>	-	120	240	ns
	propagation delay	see <u>Fig. 4</u>	10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>t</sub>	transition time	see Fig. 4	5 V	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>su</sub>	set-up time	nD to nCP; see <u>Fig. 5</u>	5 V		+25	-15	-	ns
			10 V		+25	-10	-	ns
			15 V		+20	-5	-	ns
t <sub>h</sub>	hold time	nD to nCP; see <u>Fig. 5</u>	5 V		40	20	-	ns
			10 V		20	10	-	ns
			15 V		15	8	-	ns
t <sub>W</sub>	pulse width	nCP LOW;	5 V		60	30	-	ns
		minimum width; see <u>Fig. 5</u>	10 V		30	15	-	ns
		300 <u>r ig. 0</u>	15 V		20	10	-	ns
		nMR HIGH;	5 V		80	40	-	ns
		minimum width; see <u>Fig. 6</u>	10 V		30	15	-	ns
			15 V		24	12	-	ns
t <sub>rec</sub>	recovery time	pin nMR; see Fig. 6	5 V		50	20	-	ns
			10 V		30	10	-	ns
			15 V		20	5	-	ns
f <sub>max</sub>	maximum frequency	see Fig. 5	5 V		7	15	-	MHz
			10 V		15	30	-	MHz
			15 V		22	44	-	MHz

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

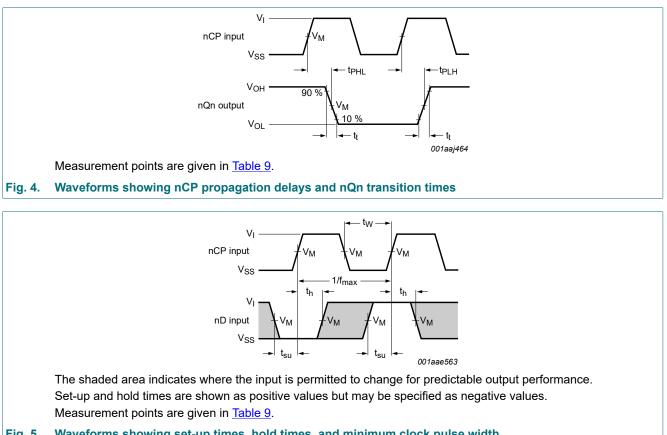
#### Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0 V$ ;  $t_r = t_f \le 20 ns$ ;  $T_{amb} = 25 °C$ .

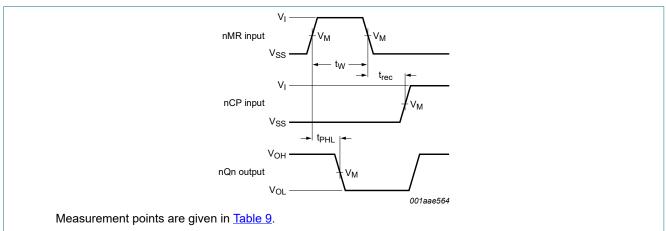
Symbol	Parameter	V <sub>DD</sub>	Typical formula for $P_D$ ( $\mu$ W)	where:
PD	dynamic power	5 V	5	f <sub>i</sub> = input frequency in MHz;
	dissipation	10 V	$P_{D} = 6300 \times f_{i} + \Sigma(f_{o} \times C_{L}) \times V_{DD}^{2}$	f <sub>o</sub> = output frequency in MHz; C <sub>L</sub> = output load capacitance in pF;
		15 V	$P_{D} = 17000 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	$V_{DD}$ = supply voltage in V; $\Sigma(C_L \times f_o)$ = sum of the outputs.

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#### Waveforms showing set-up times, hold times, and minimum clock pulse width Fig. 5.



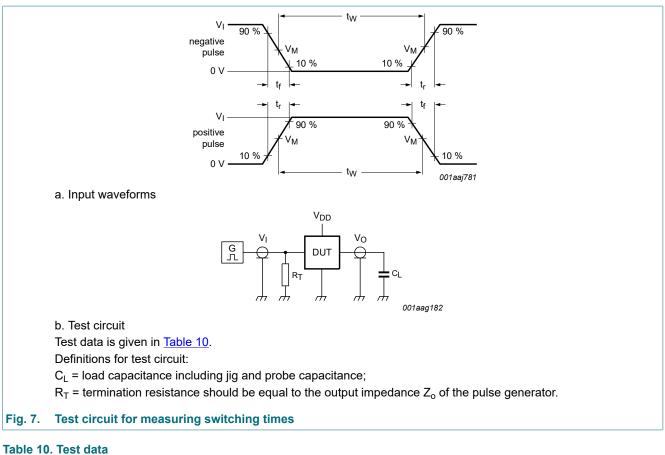
Waveforms showing MR recovery time, propagation delay and minimum pulse width Fig. 6.

### Table 9. Measurement points

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>

### HEF4015B

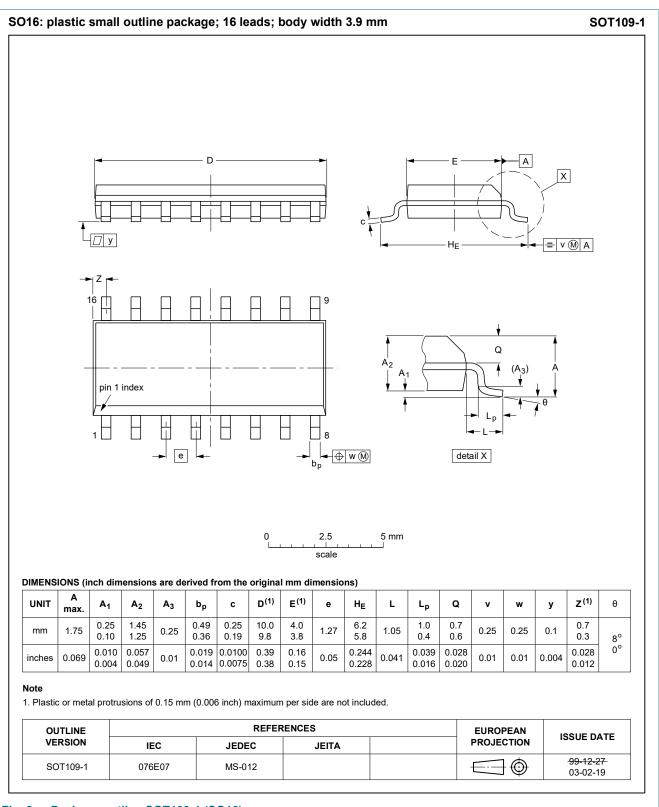
#### Dual 4-bit static shift register



Supply voltage	Input I		Load
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	$V_{SS}$ or $V_{DD}$	≤ 20 ns	50 pF

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### 12. Package outline



#### Fig. 8. Package outline SOT109-1 (SO16)

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### 13. Abbreviations

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
НВМ	Human Body Model
MM	Machine Model

### 14. Revision history

Table 12. Revision history						
Document ID	Release date	Data sheet status	Change notice	Supersedes		
HEF4015B v.10	20211126	Product data sheet	-	HEF4015B v.9		
Modifications:	<u>Section 1</u> and	<u>Section 1</u> and <u>Section 2</u> updated.				
HEF4015B v.9	20160321	Product data sheet	-	HEF4015B v.8		
Modifications:	Type number HEF4015BP (SOT38-4) removed.					
HEF4015B v.8	20111121	Product data sheet	-	HEF4015B v.7		
Modifications:	Legal pages	Legal pages updated.				
	Changes in "	<ul> <li>Changes in "General description" and "Features and benefits".</li> </ul>				
HEF4015B v.7	20110914	Product data sheet	-	HEF4015B v.6		
HEF4015B v.6	20091103	Product data sheet	-	HEF4015B v.5		
HEF4015B v.5	20090624	Product data sheet	-	HEF4015B v.4		
HEF4015B v.4	20090127	Product data sheet	-	HEF4015B_CNV v.3		
HEF4015B_CNV v.3	19950101	Product specification	-	HEF4015B_CNV v.2		
HEF4015B_CNV v.2	19950101	Product specification	-	-		

### **HEF4015B**

Dual 4-bit static shift register

### 15. Legal information

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Document status [1][2]	Product status [3]	Definition
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Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
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